

OTB Users Days 2017

Plans for asynchronous s/writing/IO/

OTB Team

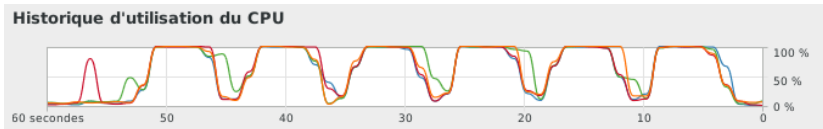


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What asynchronous means

- ▶ This is the CPU graph of running the OrthoRectification app :



- ▶ Question : what does OTB do when CPUs are not fully loaded?
- ▶ Answer : IOs!
- ▶ I do not like idle CPUs ... do you?
- ▶ Note that for the moment everything in this talk is pure **slideware**



Example 1 : Ortho-rectification

	Reading time	Processing time	Writing time
Stream 1	1.4808061 s	5.2900510 s	0.8211150 s
Stream 2	2.0999321 s	5.3412859 s	0.3260920 s
Stream 3	1.8735771 s	5.3453019 s	0.8125529 s
Stream 4	1.4494860 s	5.3393729 s	0.7880170 s
Stream 5	1.4502799 s	5.3677251 s	0.8284358 s
Stream 6	1.4794530 s	5.3115728 s	0.8141160 s
Total	9.8335342 s	31.995310 s	4.3903287 s
Percentage	21.275877 %	69.225189 %	9.4989339 %

- ▶ I/O time < processing time : expected gain = 30%



Example 2 : Pansharping

	Reading time	Processing time	Writing time
Stream 1	0.0996530 s	10.387469 s	0.3946828 s
Stream 2	0.1185460 s	10.207732 s	0.2917110 s
Stream 3	0.1487219 s	10.051636 s	0.7517421 s
Stream 4	0.1215879 s	10.134621 s	0.2930951 s
Stream 5	0.1364500 s	10.115682 s	0.5939779 s
Stream 6	0.3663129 s	10.087998 s	0.2909901 s
Total	0.9912717 s	60.985138 s	2.616199 s
Percentage	1.5346519 %	94.415041 %	4.050307 %

- ▶ I/O time \ll processing time : expected gain = 5%



Example 3 : Convert

	Reading time	Processing time	Writing time
Stream 1	0.0996530 s	0.7366901 s	0.3946828 s
Stream 2	0.1185460 s	0.7274349 s	0.2917110 s
Stream 3	0.1487219 s	0.7287521 s	0.7517421 s
Stream 4	0.1215879 s	0.7263241 s	0.2930951 s
Total	0.4885088 s	2.9192012 s	1.731231 s
Percentage	9.5060208 %	56.805501 %	33.688478 %

- ▶ I/O time \approx processing time : expected gain = 40 %

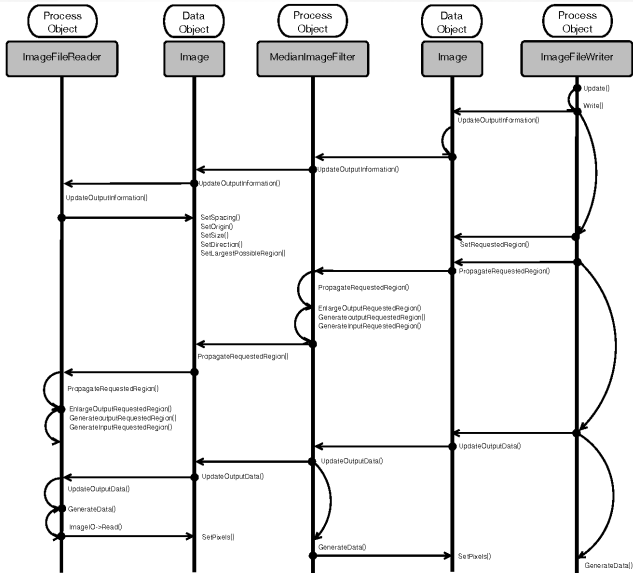


Conclusion

- ▶ I/O time vs. processing time heavily depends on the processing chain
- ▶ Expected gain in total time is between 5% and 40% (best case scenario)
- ▶ Reading time is at least as important as writing time. **We need to do both !**



A brief reminder of the pipeline



The easy part : writing

- ▶ After call to `UpdateOutputData()` for current stream, the writer passes the output buffer to the driver for writing to disk
- ▶ Making this call asynchronous with a FIFO and a separate writing thread is easy enough
- ▶ FIFO should be size-limited with a sync lock so that it does not get flowed in case reading/processing is faster than writing



The tough part : reading

Why it is more difficult

- ▶ Aim : Read next stream while processing current stream -> prefetch
- ▶ How can the reader know about requested regions for next streams?
- ▶ Constraint : communication between reader and writer -> pipeline

Proposed solution

- ▶ Writer will make several `GenerateInputRequestedRegion()` calls for one `UpdateOutputData()` call
- ▶ On the other side of the pipeline, reader will record those regions in a FIFO (limited size)
- ▶ FIFO is processed by a separate reading thread
- ▶ Upon `UpdateOutputData()`, reader will wait for the last requested tile to be read (if not already available)



C++11 to the rescue ?

Several features from C++11 might help to implement this behaviour (in `<future>`) :

- ▶ `std::async`
- ▶ `std::packaged_task`
- ▶ `std::promise`

The tricky part is that our objects are not stateless



Conclusion and thoughts

- ▶ Gain will also be highly dependent on the hardware :
 - ▶ Single or different hard drive for input and output
 - ▶ RAID, GPFS ...
 - ▶ Can a standard hard-drive read and write simultaneously ?
- ▶ System already does a lot of caching, should we really add another layer ?
- ▶ Trade memory for speed
- ▶ Is this worth the price (complexity of reader, writer, side effects ...)
- ▶ Reader / Writer are quite complex already -> careful not to break anything

